Design and Analysis of Sensory Informed Incomplete Block Designs

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### Incomplete Block Design

- Observe a person's response to 12 different products (randomized block design)
- However for wine and other alcohol beverages products it is difficult to obtain an individual response to several products because of intoxication, carry-over, adaption and fatigue.
- To compensate use balanced incomplete block designs.
- The goal is to determine if there is any clusters or grouping within the data.

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### Sensory-Informed Design: Bread Study

### Sensory Profile

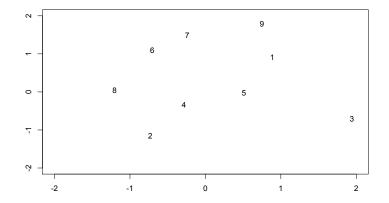
- 10-13 trained panelists
- Each panelists evaluates the 12 different Bread products on 42 attributes.
- Attributes for crumb
  - Springiness
  - Firmness
  - Moistness
  - Chewiness
  - Particles

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# Products in the Sensory Space



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## **Mixture Modelling**

 To find segments in the data, we assume the liking scores arise from a Gaussian mixture

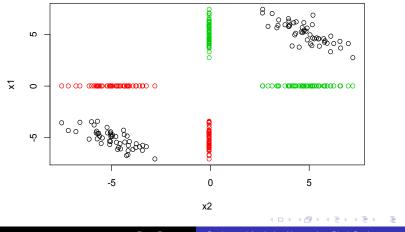
$$m{Y} \sim \sum_{g=1}^{G} \pi_{g} f(m{y}|\mu_{g}, \Sigma_{g})$$

- If we had a complete-block design we would just apply standard methodology to this problem.
- The literature commonly suggests imputation or some variation thereof, for incomplete blocks.

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## Imputation using the Average



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- However, it is possible to estimate a covariance matrix when some data are missing.
- We can do this via the expectation-maximization (EM) algorithm.
- This approach is particularly useful when the covariance matrix has a special structure.
- And even more so when

$$\mathbf{\Sigma}_g = \mathbf{\Sigma}$$

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### **Covariance Structures**

Mclust models - (Mclust in R)

$$oldsymbol{\Sigma}_{oldsymbol{g}} = \lambda_{oldsymbol{g}} oldsymbol{D}_{oldsymbol{g}} oldsymbol{A}_{oldsymbol{g}} oldsymbol{D}_{oldsymbol{g}}^T$$

• Factor Analyzers - (pgmm package in R)

$$\mathbf{\Sigma}_g = \mathbf{\Lambda}_g \mathbf{\Lambda}_g^{\mathcal{T}} + \mathbf{\Psi}_g$$

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# Conditional Distribution of Missing Data

 To use EM algorithm we need to calculate the sufficient statistics for the missing data.

$$X_1 | X_2 = x_2 \backsim MVN(\mu_1 + \Sigma_{12} \Sigma_{22}^{-1} (x_2 - \mu_2), \Sigma_{11} - \Sigma_{12} \Sigma_{22}^{-1} \Sigma_{21})$$

- However, we have to calculate the expected sufficient statistics for the missing data in each row.
- This amounts to *m* choose *k* different matrix inverses.
- For the bread data 12 choose 6 =920 matrix inverses.
- Complete E-steps are not computationally feasible.



### Incremental E-step or E-Step by column

- If start with the missing data  $x_i = (x_{i1}, x_{i2}, NA, NA)$  and fill in the missing data with randomly generated observations.
- For for a particular row we say x̂<sub>i</sub> = (x<sub>i1</sub>, x<sub>i2</sub>, x̂<sub>i3</sub>, x̂<sub>i4</sub>). So, now we have a complete dataset.
- Go by column and update each estimated observation via

$$\hat{\mathbf{x}}_{i,j} = \mu_j + \Sigma_{j,-j} \Sigma_{-j,-j}^{-1} \left( \hat{\mathbf{x}}_{i,-j} - \mu_{-j} \right)$$

• e.g.

$$\hat{x}_3 = \mu_3 + \Sigma_{3,-3} \Sigma_{-3,-3}^{-1} (\hat{x}_{-3} - \mu_{-3})$$

where  $\hat{x}_{-3} = (x_{i1}, x_{i2}, \hat{x}_{i4})$ 

• If we perform this iteratively then

$$(\hat{x}_3, \hat{x}_4) \rightarrow \mu_{(3,4)} + \Sigma_{(3,4),(1,2)} \Sigma_{(1,2),(1,2)}^{-1} (x_{(1,2)} - \mu_{(1,2)})$$

# EM by column

If we have the inverse matrix of Σ

$$\Sigma = \begin{bmatrix} \sigma_{1,1} & \Sigma_{1,-1} \\ \Sigma_{-1,1} & \Sigma_{-1,-1} \end{bmatrix} \text{ and } \Sigma^{-1} = \Theta = \begin{bmatrix} \theta_{1,1} & \Theta_{1,-1} \\ \Theta_{-1,1} & \Theta_{-1,-1} \end{bmatrix}$$
$$\frac{1}{\theta_{1,1}} \Theta_{1,-1} = \Sigma_{j,-j} \Sigma_{-j,-j}^{-1}$$

- This result is possible due to a relationship between the Matrix Inverse and Schur Complement of a matrix
- We now have an incremental E-step for the 1<sup>st</sup> moment.
- We can obtain a similar result for the 2<sup>nd</sup> moment.

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 From Neal and Hinton (1998) the EM can be viewed as minimizing

$$F(N_{z}, \mathbf{x}_{i}, \theta) = logL(\mathbf{x}_{i}|\theta) - D_{\mathsf{KL}}(N_{z}||N_{z,\mathbf{x}_{i}})$$

• E-step can be viewed as minimizing the Kullback-Leibler (KL) divergence between the missing data distribution and the conditional distribution of the missing data given the observed data.

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- Iris Dataset.
- Bread Dataset.

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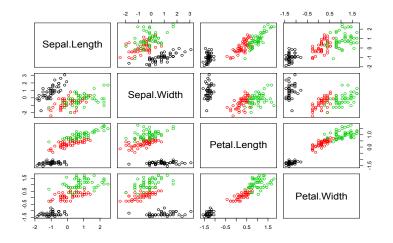
### Design Analysis Application Iris Bread Iris Dataset

- One of the most famous data sets in statistics.
- Four measurements on three types of flowers.
- We standardized the data and for each observation we randomly removed two measurements.

SepalLength	Sepal.Width	Petal.Length	Petal.Width	
		-1.34	-1.31	
-1.14		-1.34		
	0.33		-1.31	
-1.50	0.01			
		-1.34	-1.31	
-0.54			-1.05	
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### **Original Iris Dataset**



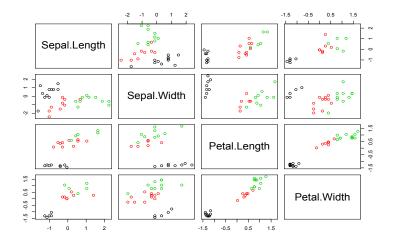
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**Iris** Bread

### **Incomplete Iris Data**



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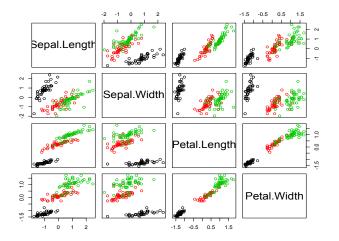
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**Iris** Bread

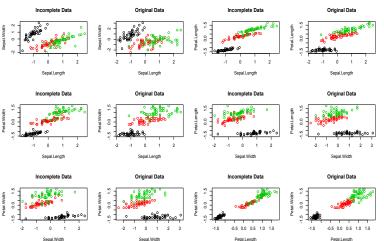
### Incomplete Iris Data with Imputed Values



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## Comparison - Imputed Incomplete and Original Data



Sepal.Width

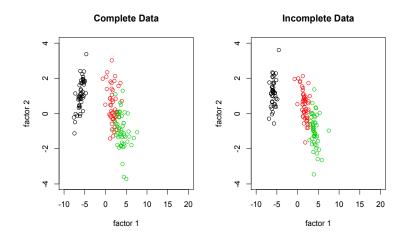
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### **Iris** Bread

### Comparison of the Latent Space - Iris Data



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Comparison of clustering results from using the incomplete iris data and the iris data.

	1	2	3
1	50	0	0
2	0	47	0
3	0	3	50

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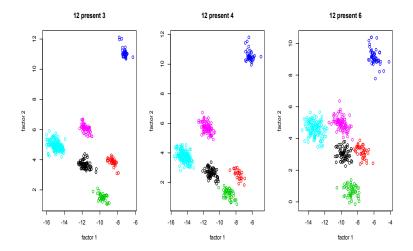
- 420 consumers.
- 12 white breads.
- Each individual evaluated 6 breads within a sensory informed incomplete block design.
- Present-3 and present-4 designs were nested within the present-6 design.
- Six groups and two factors were chosen using the Bayesian Information Criterion (BIC).

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#### lris Bread

### Latent Space - Bread Liking Scores



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- We can find MLEs using incremental EM.
- We can obtain a reasonable estimate of the latent space using only incomplete data.
- This methodology can be used for imputation.

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